



# R&D Webinar - AFOSS-DC Project Outcomes Designing the electrical substations of the future

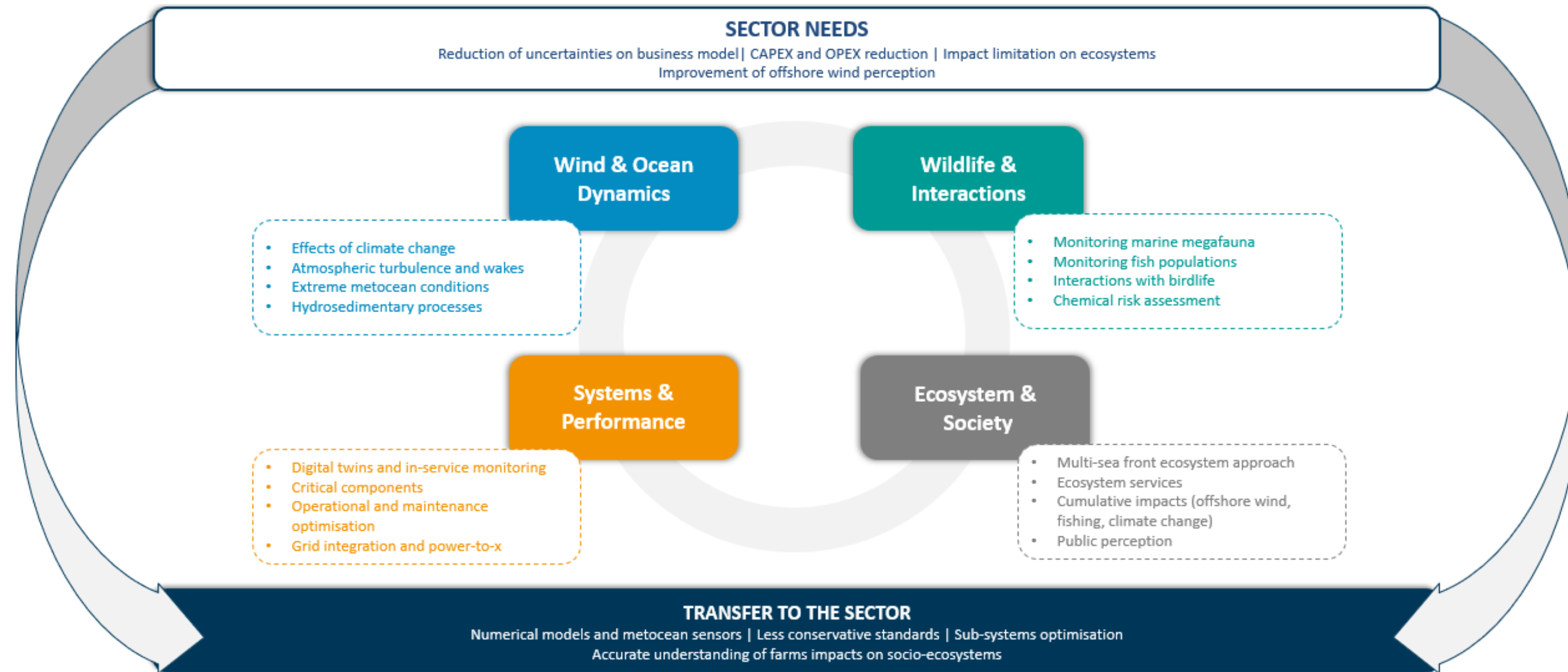


# Using TLP technology for Floating Offshore Sub-Station : feedback on design and basin test campaign

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- Presentation of France Energies Marines
- TLP concept : reminder of the technology and potential advantages for FOSS
- Design : specification and results
- Basin test campaign
- Conclusion / outcomes

- FEM (France Energy Marine) is the French Research and Innovation Institute dedicated to Offshore Wind.



# TLP concept

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- TLP means *Tension-leg Platform*.

Comparatively to *Semi-submersible* platform, the « mooring » lines called **tether/tendons** are vertically moored.

Here are the potential advantages/drawbacks of such a technology :

- **Advantages :**
  - Reduce vertical movements (and maybe accelerations ?) which can be beneficial for both electrical equipments and cables
- **Drawbacks :**
  - Nonlinear effects (springing/ringing) to be taken into account
  - Installation might be more complicated than other technology

# TLP Design

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- **Main objectives** of this TLP design work :
  - Provide a **basic design** which can be validated early to start the scale model construction for the basin tests
  - Satisfy the design criteria with comfortable margin, given the early stage and associated hypothesis
- **Environmental conditions** :
  - 3 water depths : **400 m (base case)**, 150 m and 1000 m
  - **100-yrp wave data (Atlantic coast)**
  - 100-yrp wind speed @10 m
  - 10-yrp surface current speed
- **Main design criteria** :
  - Adapt to topside mass and dimensions
  - Maximum dimension to ease construction and installation
  - **Positive airgap** during any lifecycle phase and keel emergence superior to 3m
  - Stability requirements following DNV-OS-C301 (for free floating phase) and DNV-OS-C205
  - Maximum acceleration levels (for electrical equipment) and horizontal offset (for cables)

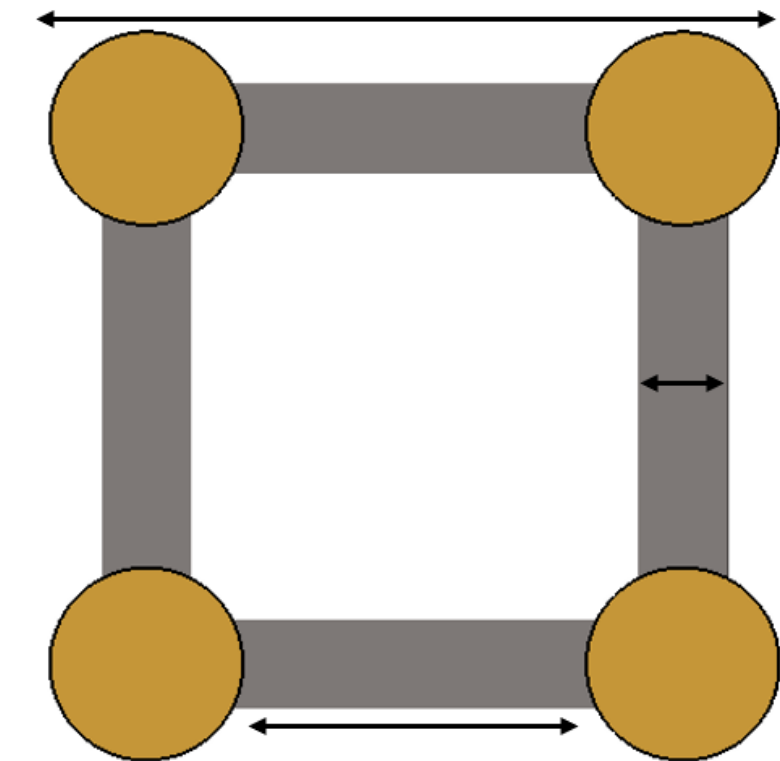
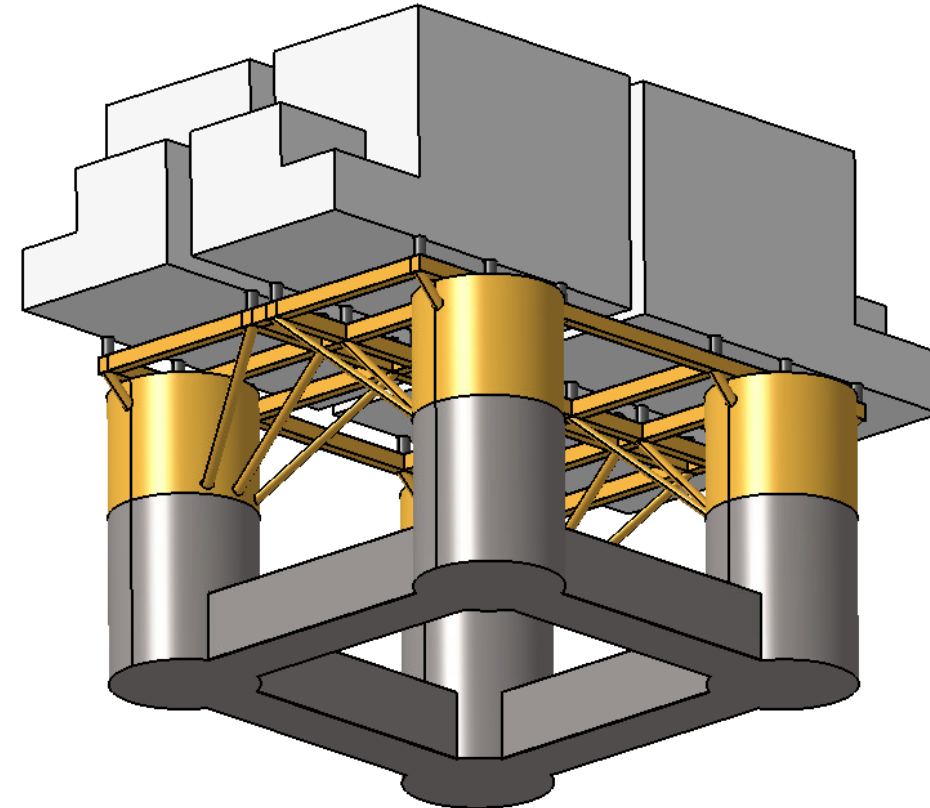
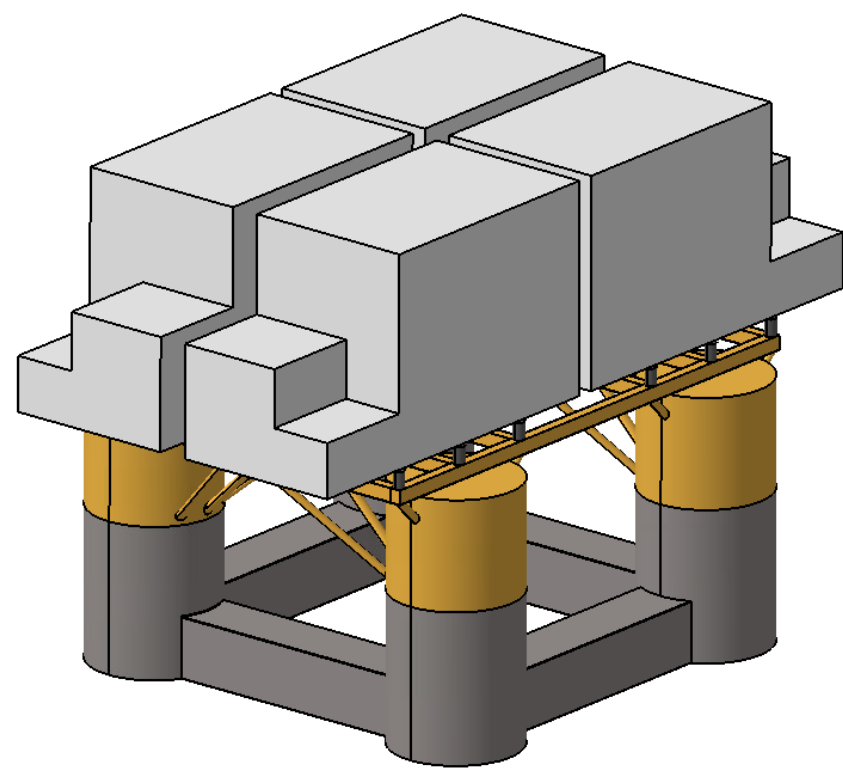
	Maximum dimensions
Maximum Length	200 m
Maximum Width	58 m
Maximum Height	66 m
Maximum Draft at yard	9 m

FOSS Maximum allowable dimensions

	Maximum allowable motion
Horizontal acceleration	4.0 m/s <sup>2</sup>
Vertical acceleration	3.5 m/s <sup>2</sup>
Tilt angle	15 deg
Horizontal offset	Max (30 m ; 10% of water depth)

FOSS Maximum allowable motions

- TLP global geometry (floater and transition piece) :



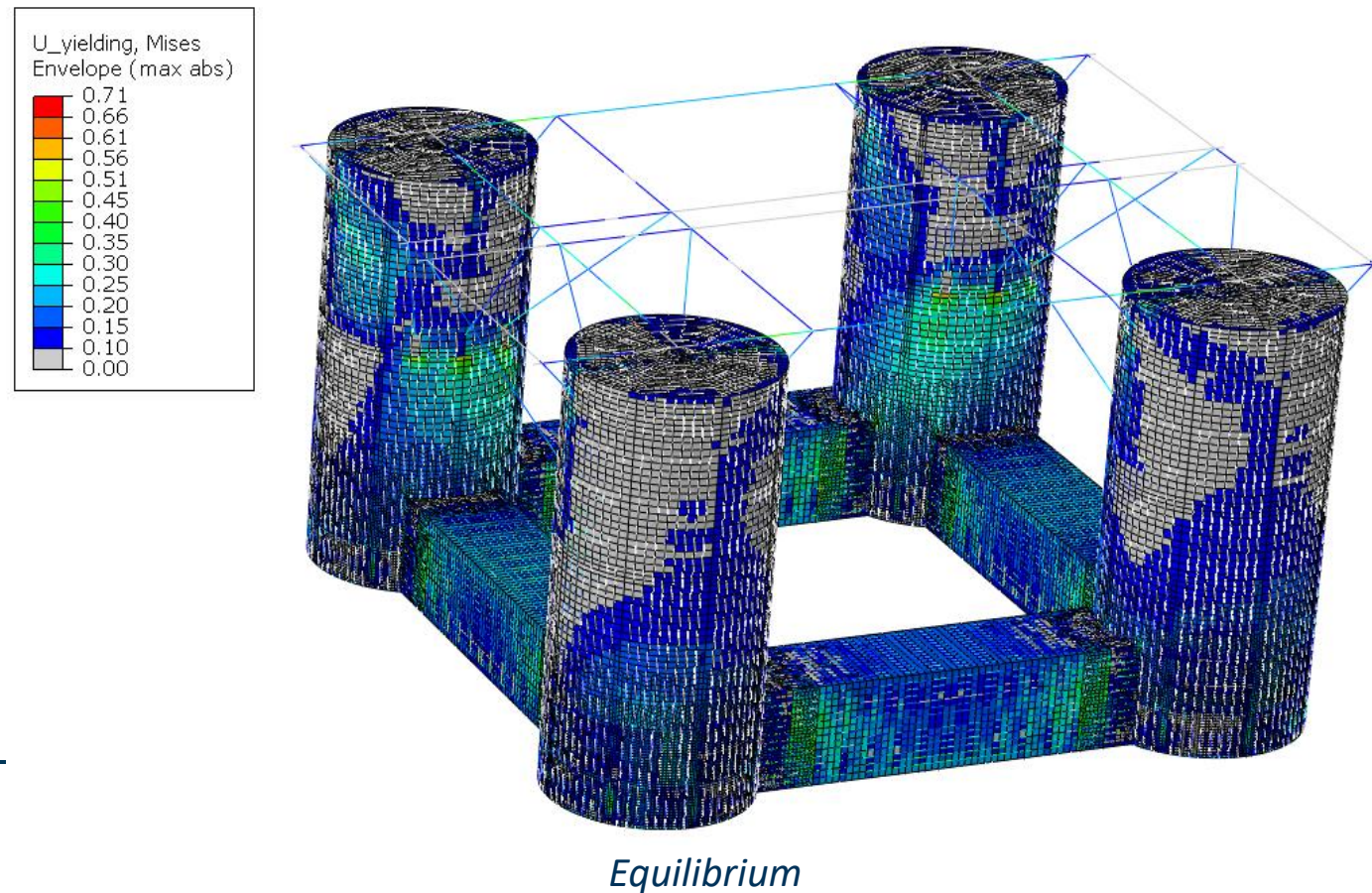
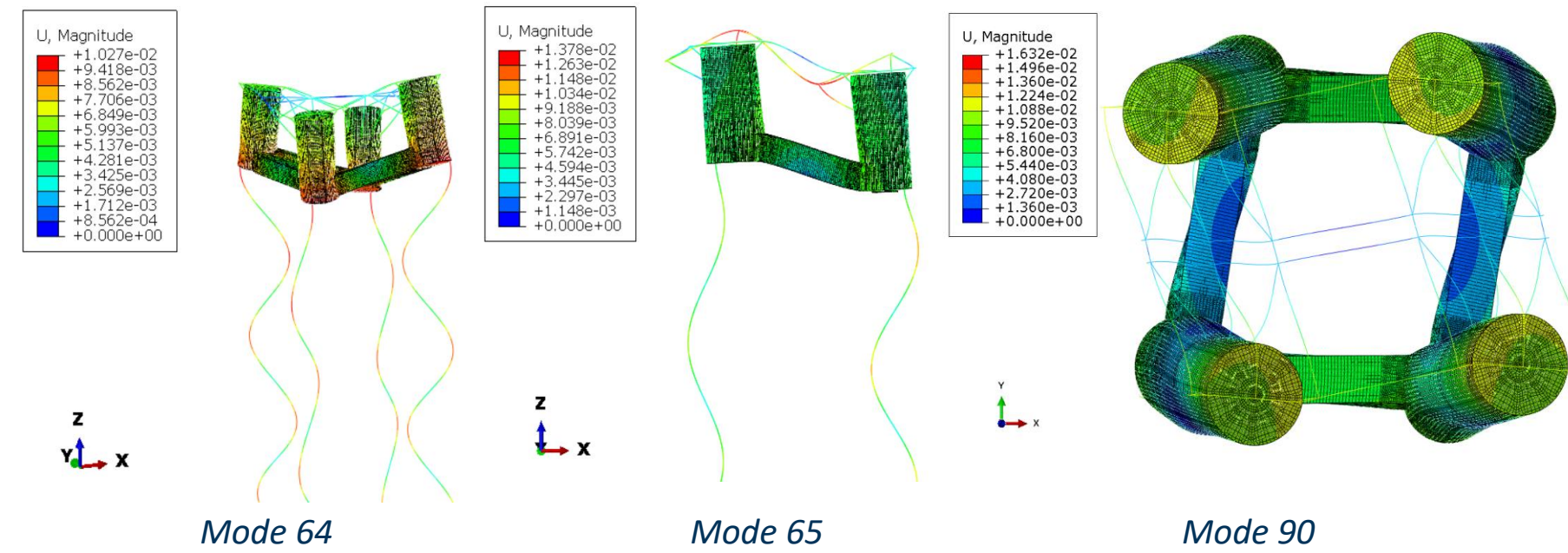
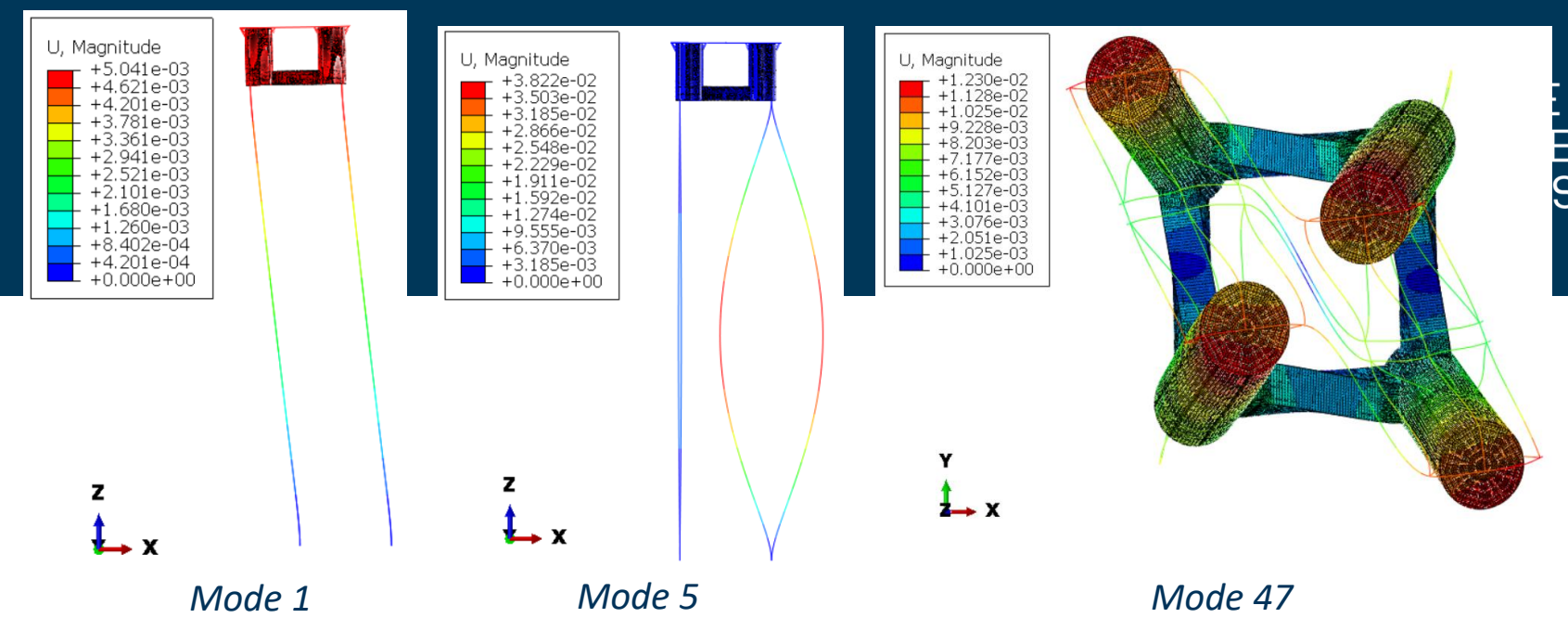
- Draft : 26 m (in place), 20 m (towing)
- Mass estimation :

Element	Mass (te)	VCG (m)
TP (no margin for welding)	3 032	43.0
Hull (no margin for welding)	13 335	15.6
Ballasted hull with TP	18 192	18.7

**NB:** this design is preliminary and should be optimized in a detailed design

# Design results : Structural studies

- Both static and dynamic structural analysis have been conducted :
  - Von mises criteria have been passed
  - Modes up to 100 have analyzed and compared to topside structural modes
  - Thickness inside of the main elements the hull have been defined → mass weight report has been updated !

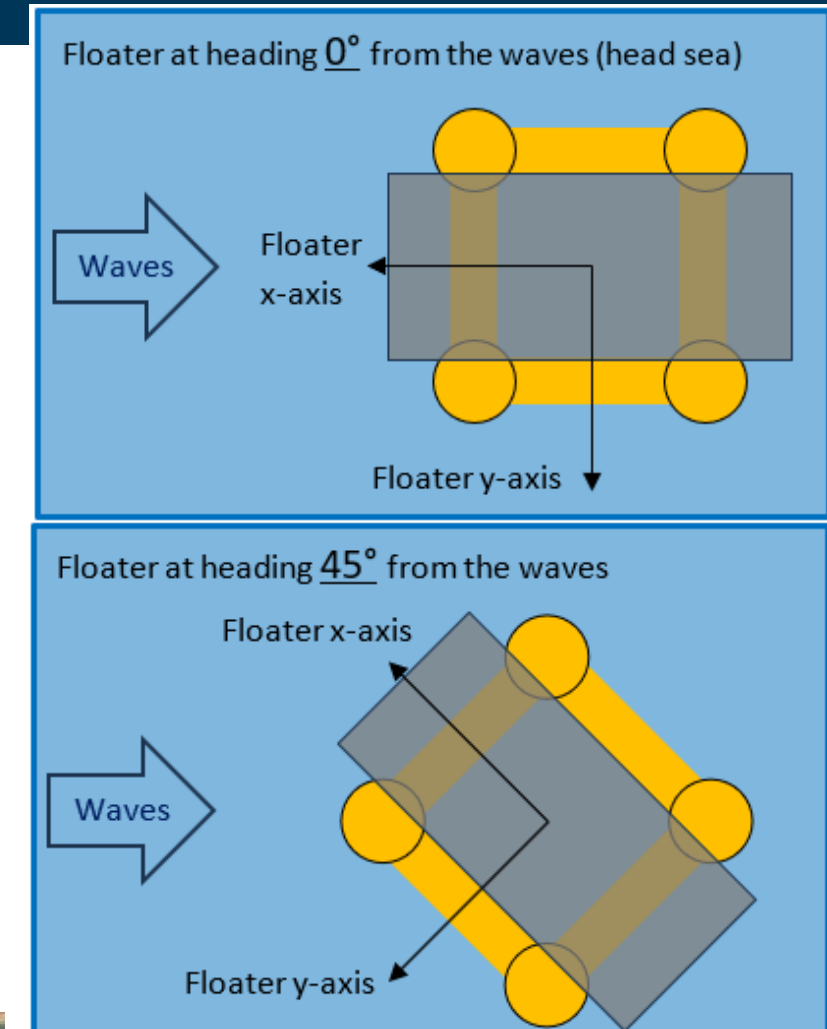
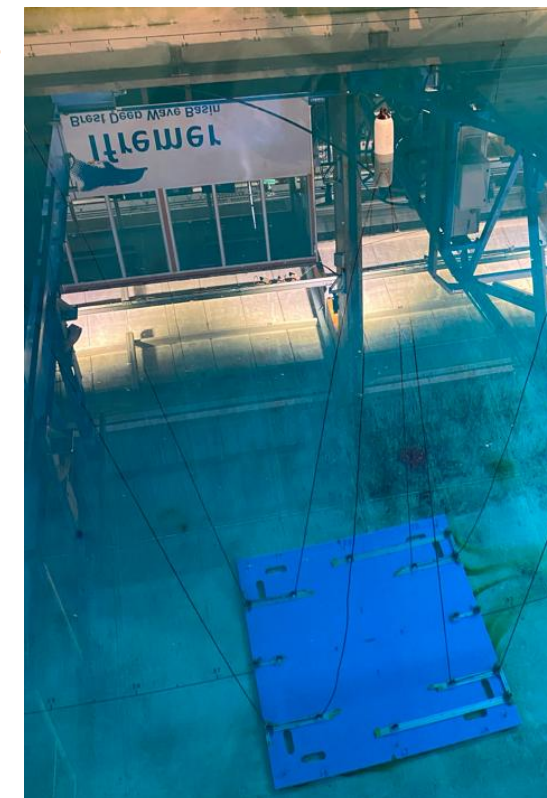
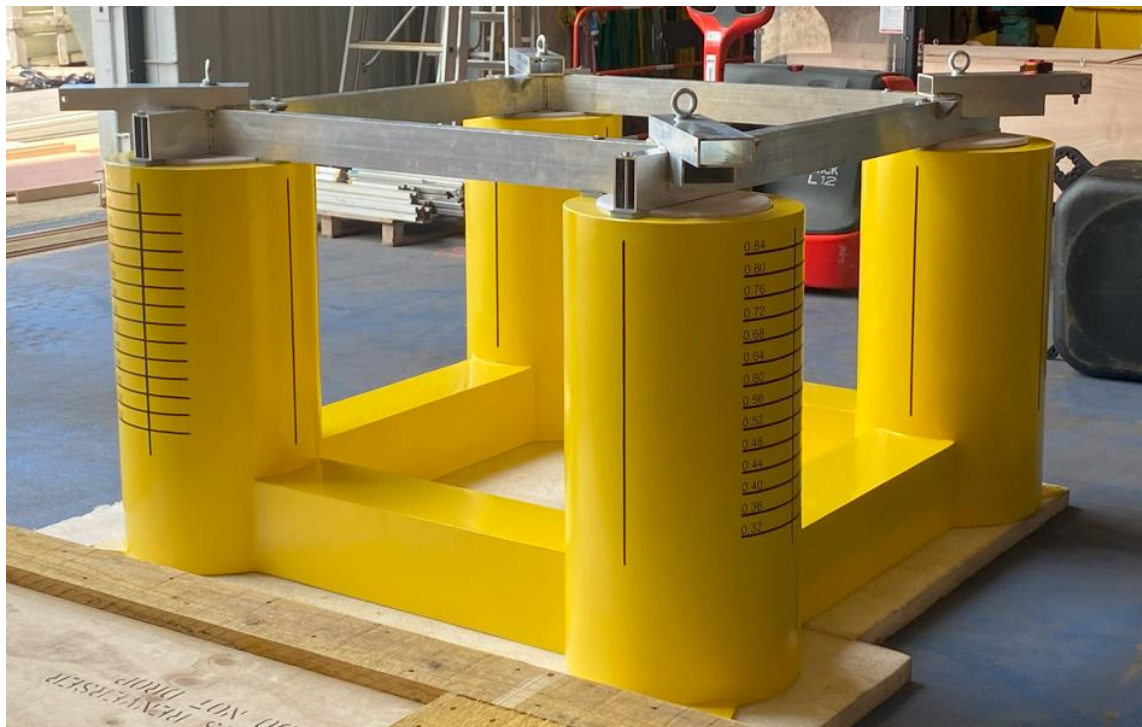


# TLP Basin test campaign

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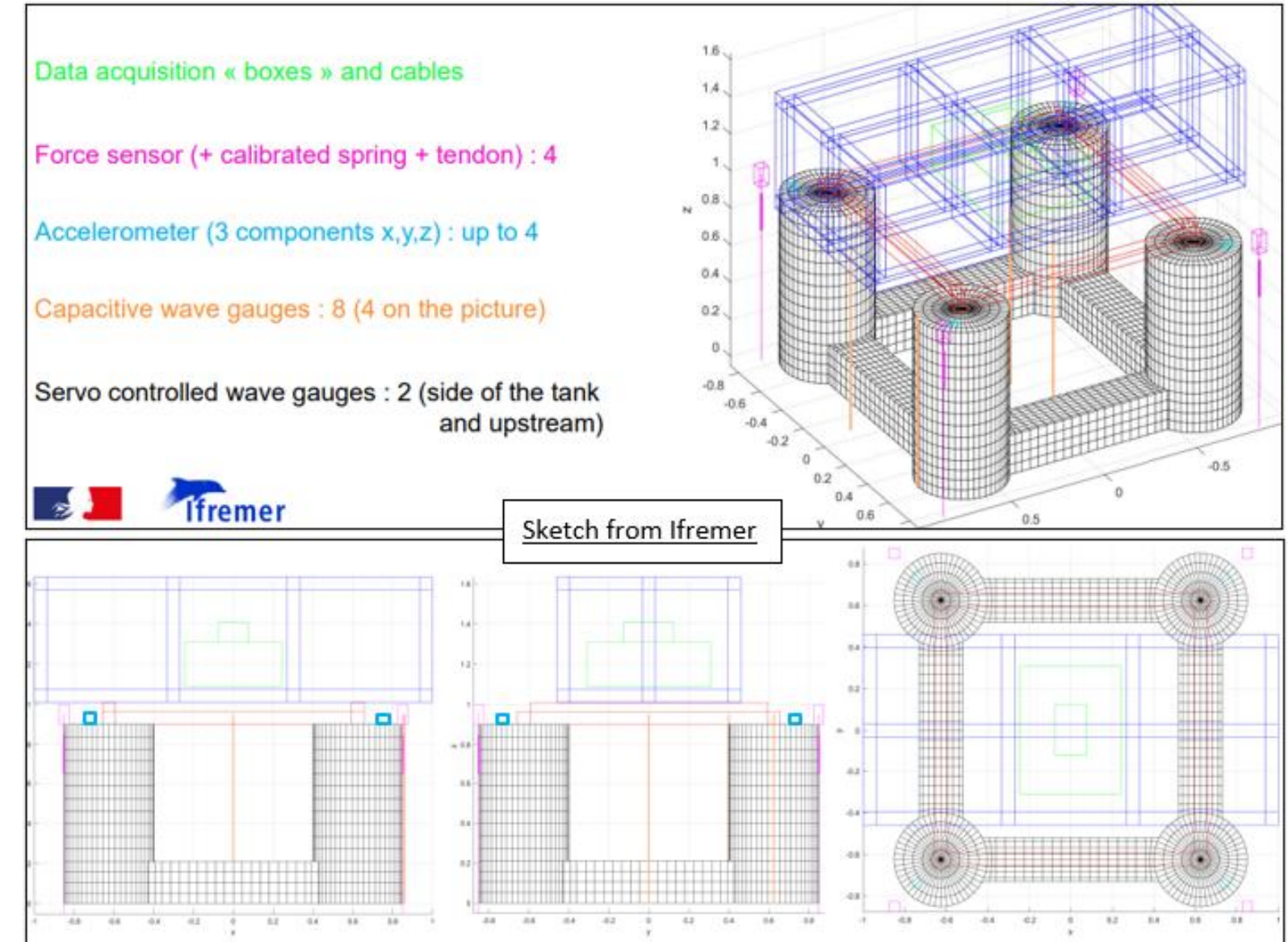
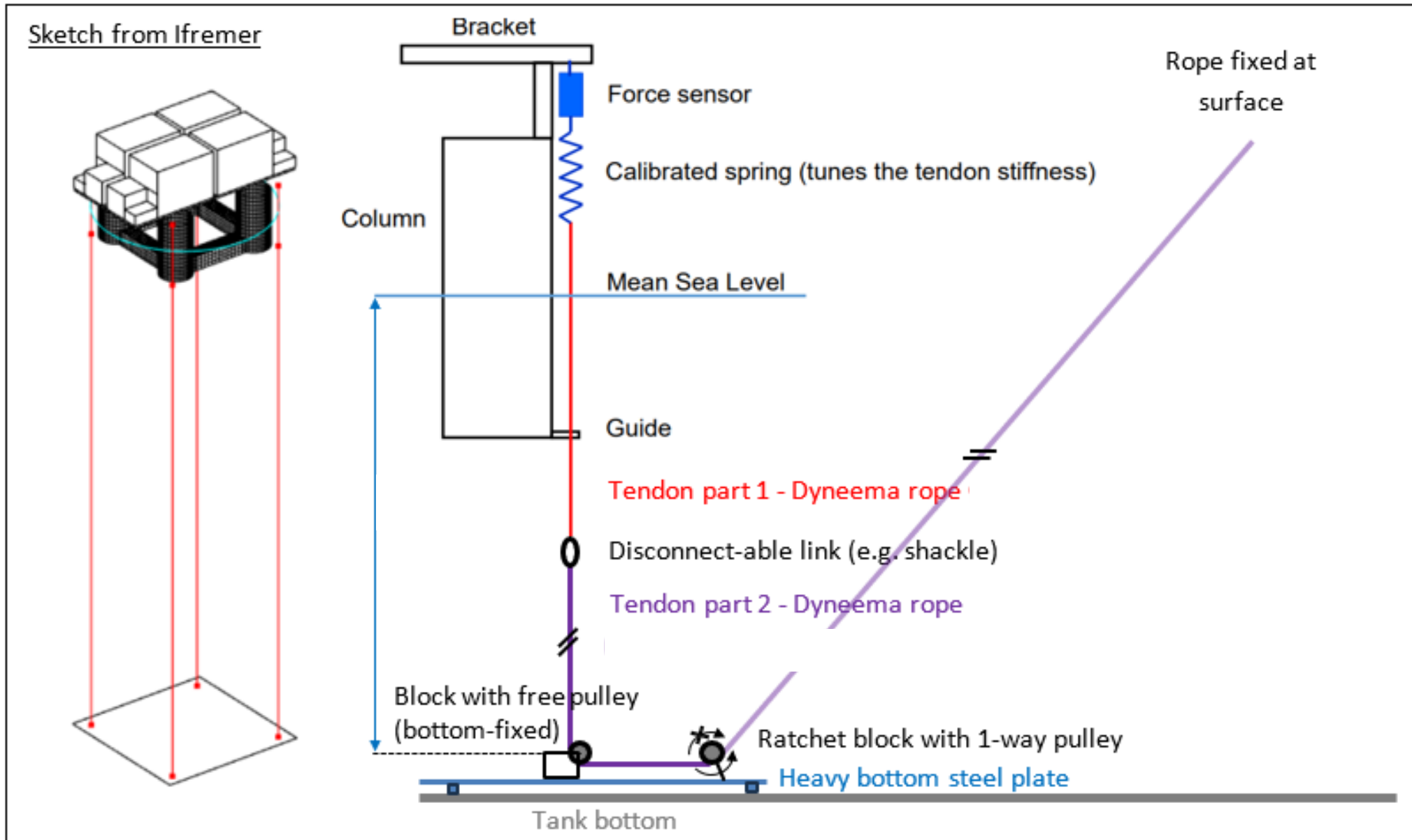
# Basin test campaign preparation : objectives/program, mock-up design and instrumentation (1/2)

- Main Objectives :
  - Assess whether non-linear effects are present in the system response in the wave conditions considered
  - Provide experimental results for this platform concept:
    - Tendons' tension and platform motions and accelerations to evaluate the accuracy of the numerical analysis
    - Free-surface elevation and resulting air-gap to evaluate the accuracy of numerical assessment
    - To assess the sensitivity of the global response to the tendons' stiffness or water depth.
- Scale 1:50, Froude scaling.
- Test program (over 200 tests during 3 weeks)
  - Still water tests: pull-out and decays.
  - Regular waves tests, at  $0^\circ$  and  $45^\circ$ , 3 tendons stiffness for 3 different water depths
  - Irregular waves tests, at  $0^\circ$  and  $45^\circ$ , 3 tendons stiffness for 3 different water depths
  - Focused waves tests, at  $0^\circ$  and  $45^\circ$ , 3 tendons stiffness for 3 different water depths

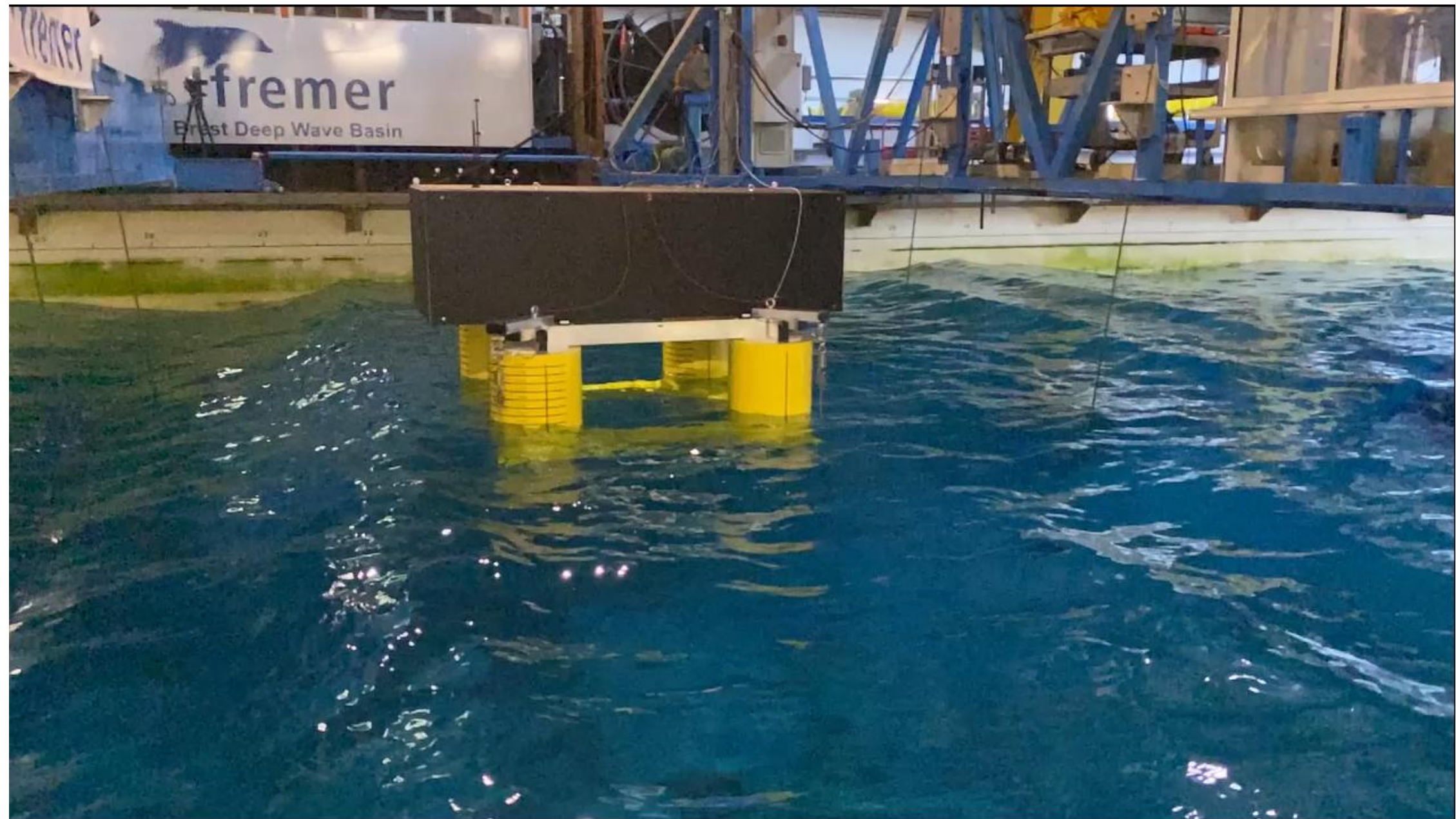
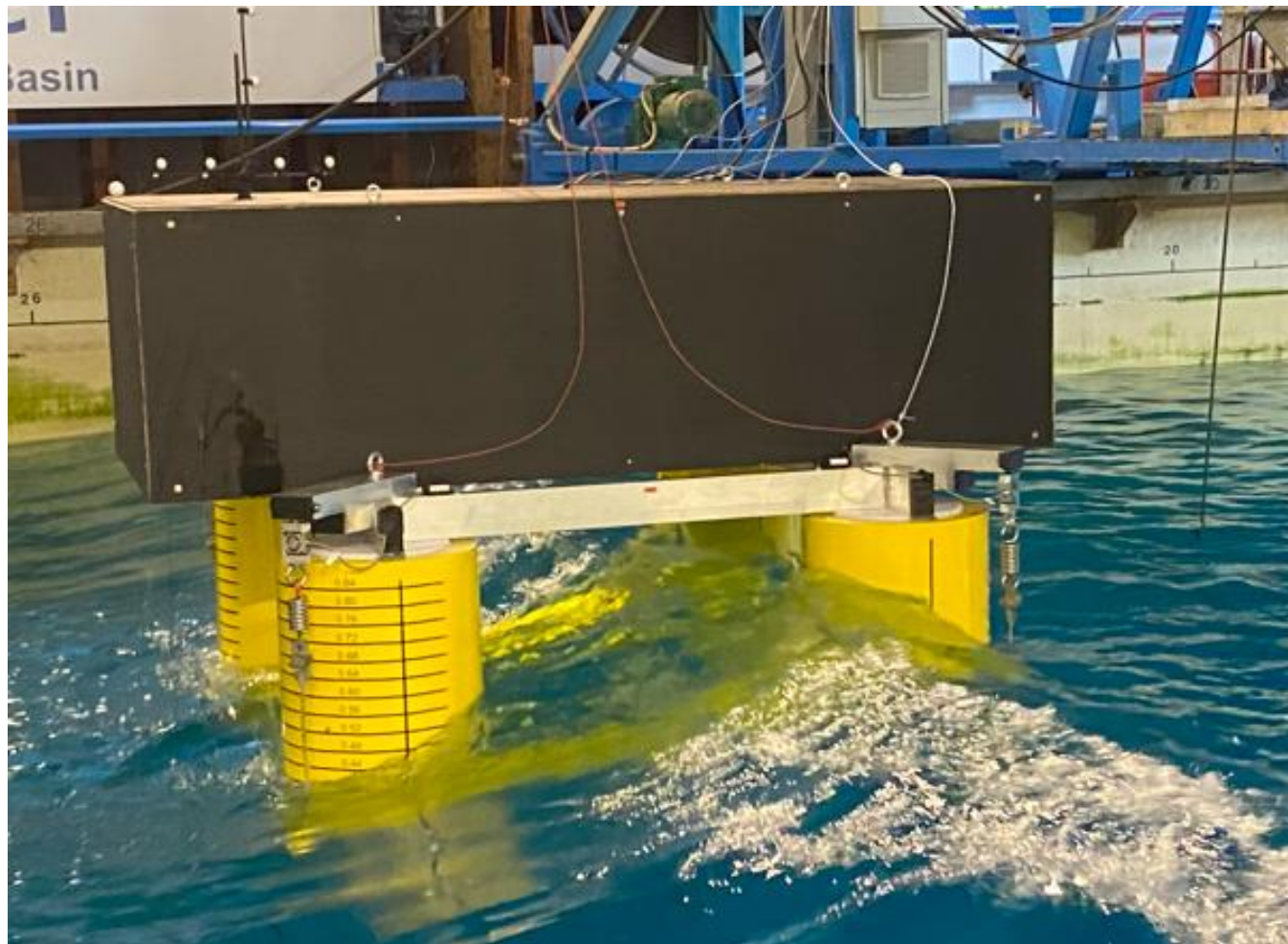


# Basin test campaign preparation : objectives/program, , mock-up design and instrumentation (2/2)

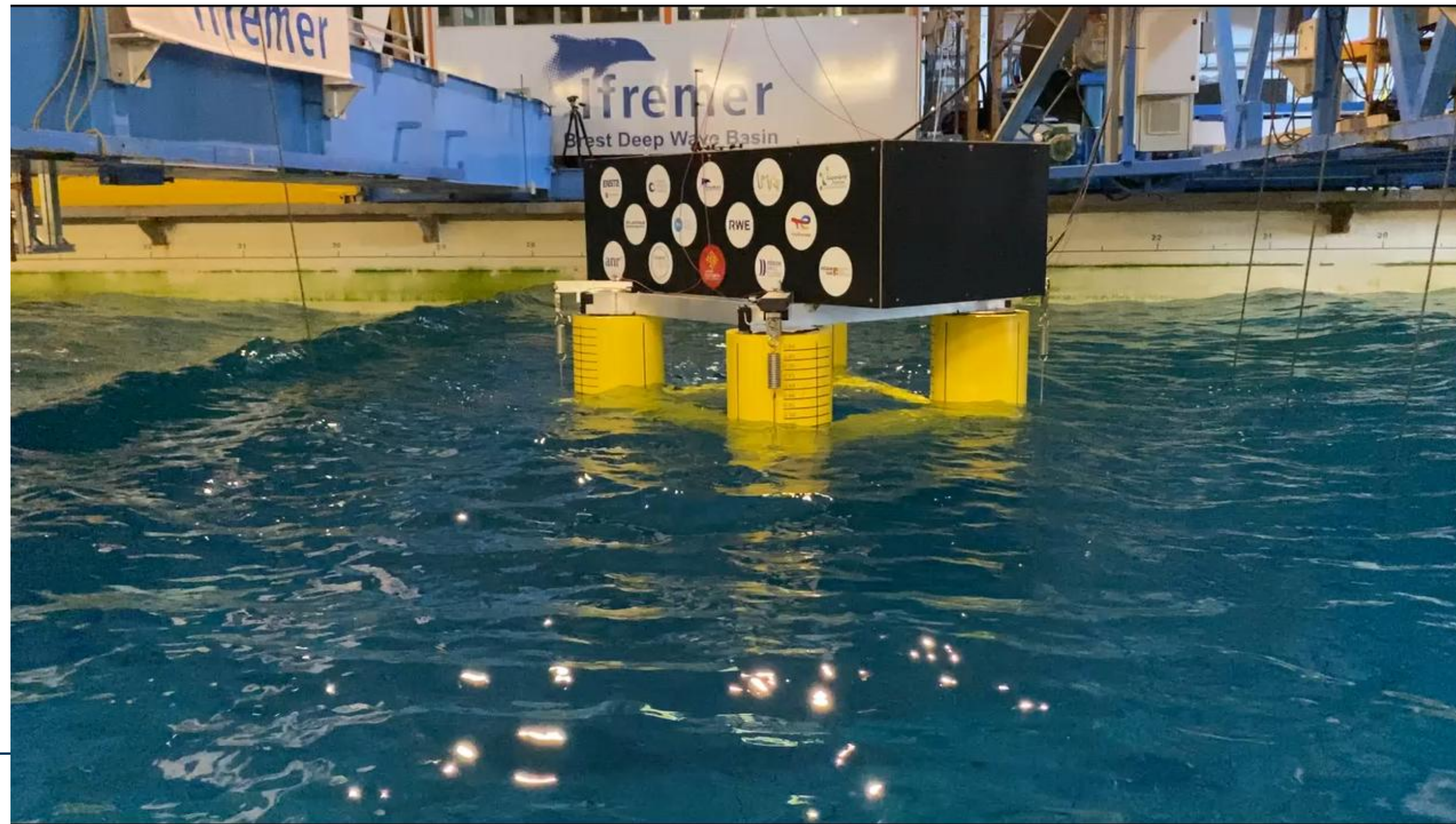
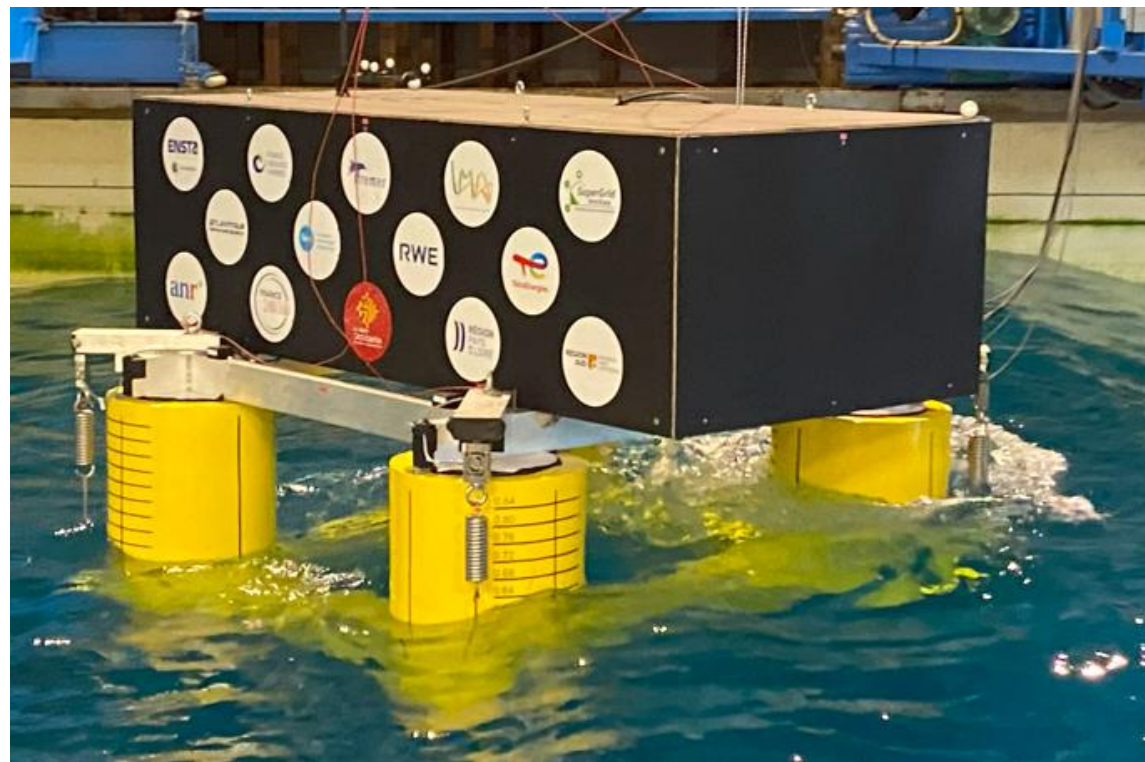
- Explanation of experimental design and instrumentation :



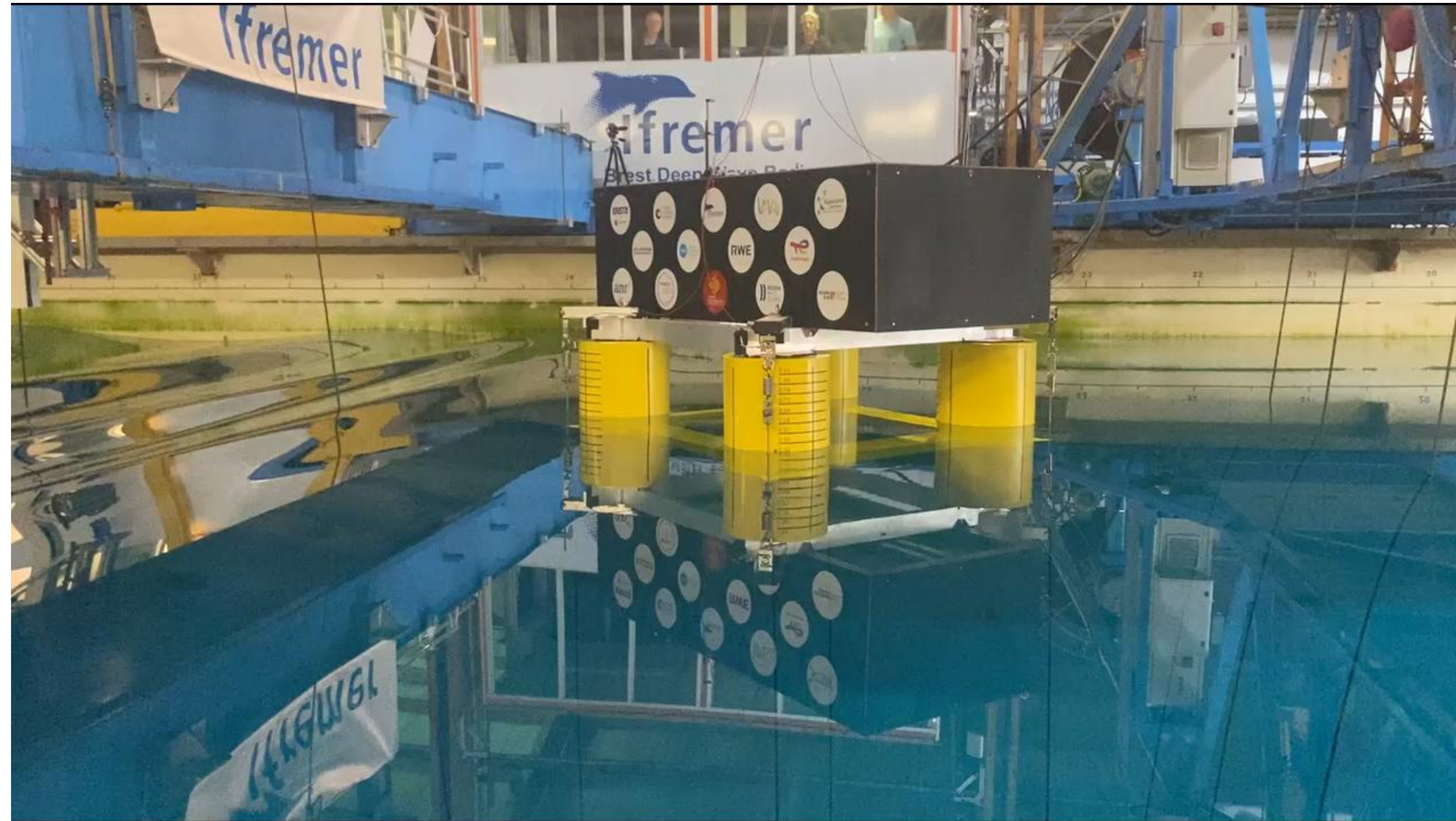
- 100-yr conditions, irregular waves Hs 13.9m, Tp 17s (test 063), 0deg, tendons stiffness 400m
  - « flat » motions



- 100-yr conditions, irregular waves Hs 13.9m, Tp 17s (test 214), 45deg, tendons stiffness 1000m
  - Visible pitch motion



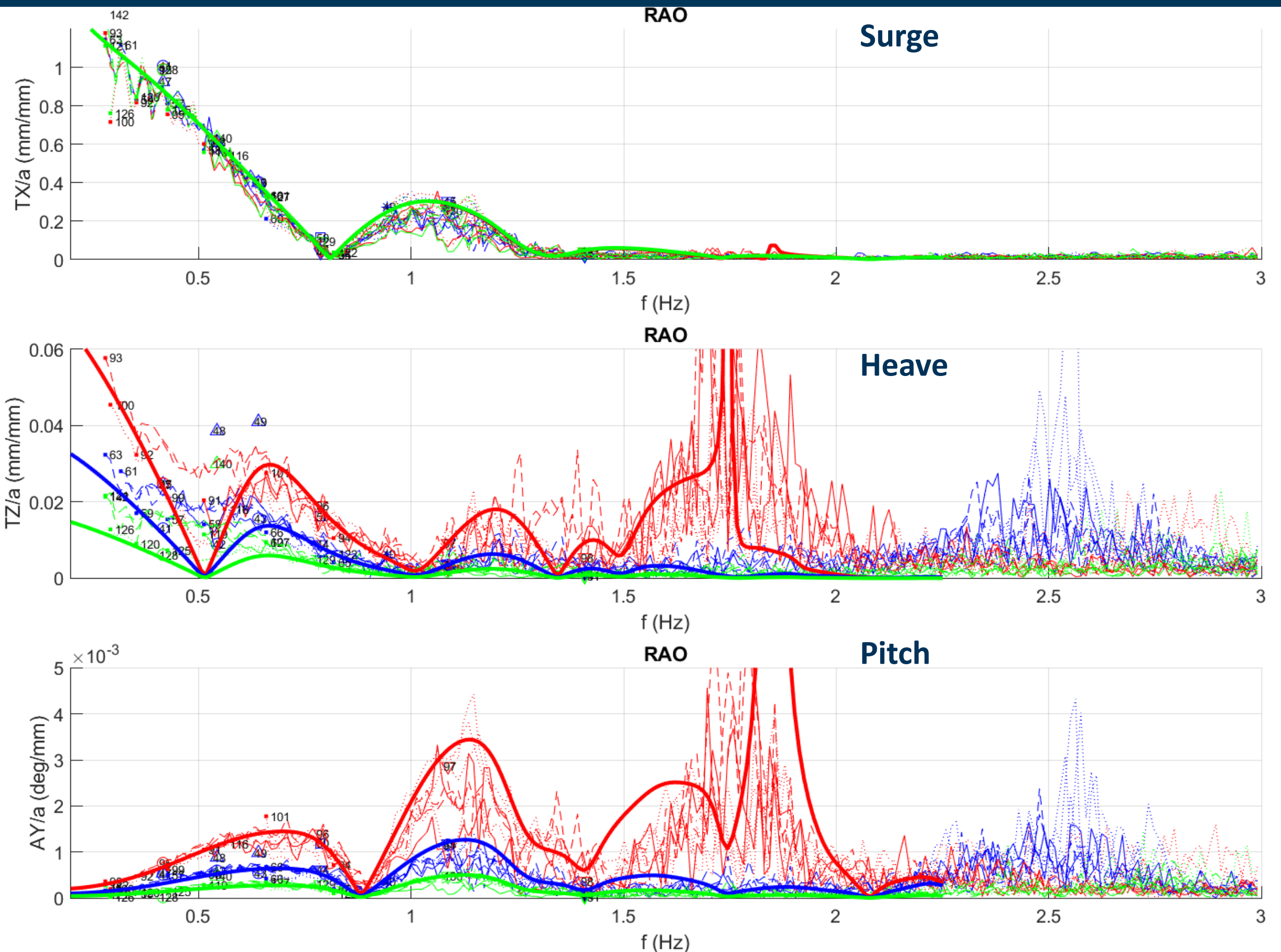
- Focused waves
- Success in realization  
Steep wave (not breaking)  
Variation in « focus point »



- Motions
- Transfer functions
- on regular and
- irregular waves
- Incidence = 0 °

150 m water depth  
 400 m water depth  
 1000 m water depth

Marker : regular waves  
 Lines : irregular waves  
 Thick lines : Hydrostar  
 diffraction and radiation  
 software

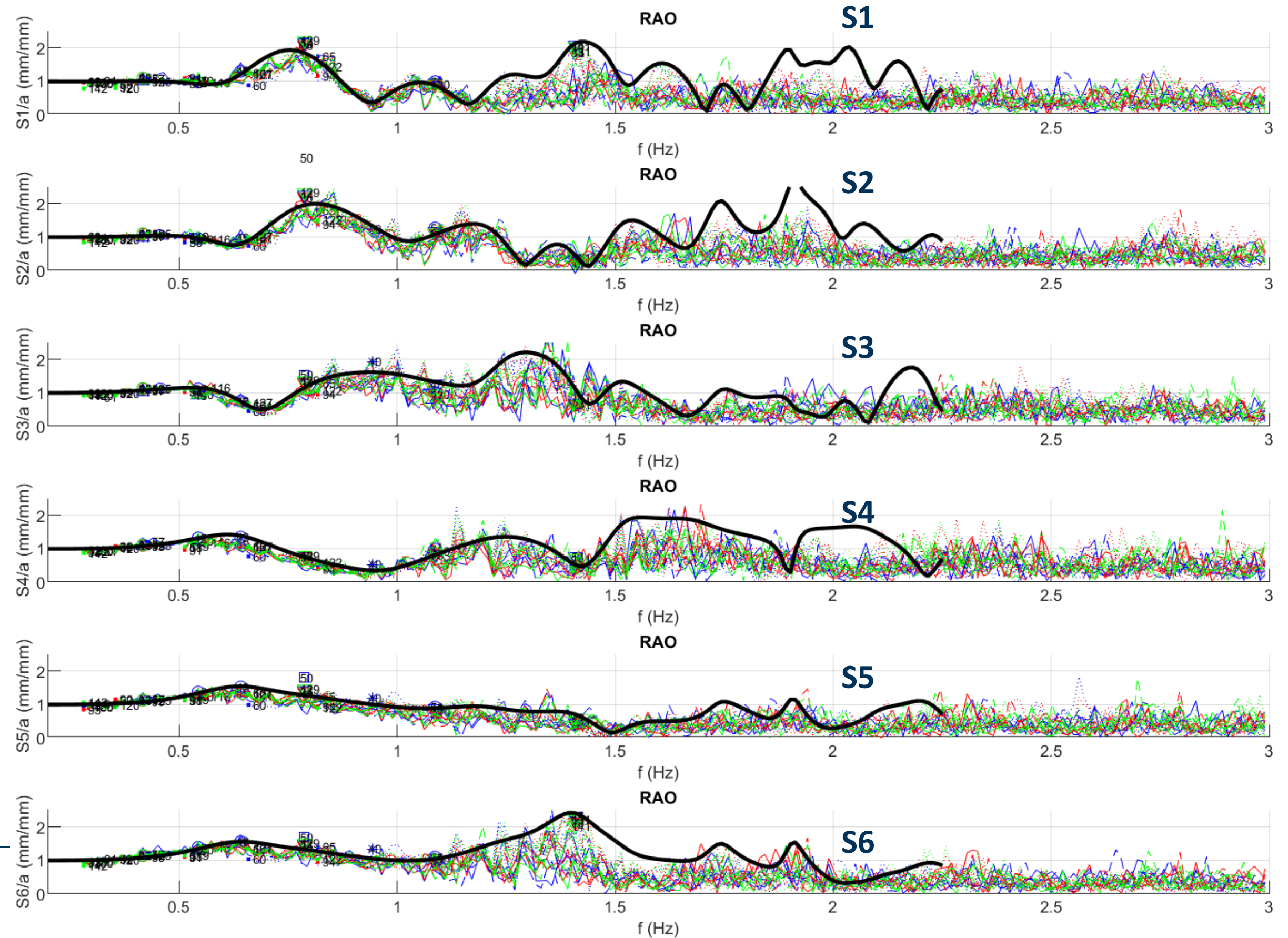


# Basin test campaign : Free surface elevation RAOs

- Free surface elevations
- Transfer functions
- on regular and
- irregular wave
- Incidence = 0 °

150 m water depth  
400 m water depth  
1000 m water depth

Marker : regular waves  
Lines : irregular waves  
Thick lines : Hydrostar



- **Basic design** (including structural design) have been successfully done and **all criteria of design have been met.**
- **Basin test campaign has been run** and **RAO** are **in accordance** with what has been calculated during design.
- **Non-linear effects have been identified** at certain wave conditions (focus waves)

### Future work :

- Potential updates if weight estimation is updated
- Possible design updates if location hypothesis (Water depth / Metocean conditions) changes
- Continue analysis on non-linear effects on TLP basin test campaign
- The concepts (TLP / semi-sub') can be compared depending on the site/conditions

Thank you for your attention!

